

ECR3030

Technical Specifications

| Technology | |
|------------------------------------|---|
| travel mechanism | inertial piezo drive |
| positioner type | rotator |
| Size and Dimensions | |
| footprint; height | 30x30; 13.5mm |
| max installation space | 30x30; 13.5mm |
| weight (aluminium version) | 28 g |
| weight (stainless steel version) | 66 g |
| Materials | |
| positioner body | Aluminum |
| positioner body (/HV, /UHV) | stainless steel |
| actuator | PZT ceramics |
| connecting wires | copper, jacket: RT: silicon, HV/UHV: fiberglass |
| bearings | stainless steel |
| Options | |
| environmental options | /RT |
| Load (@ ambient conditions) | |
| maximum load | 20 N |
| maximum dynamic torque around axis | 2 Ncm |
| Coarse Positioning Mode | |
| input voltage range | 0 - 60 V |
| travel range (step mode) | 360 ° |
| maximum drive velocity @ 300 K | 10 °/s |
| typical minimum step size @ 300 K | 0.4 m° |
| | |

| Fine Positioning Mode | | |
|--|-------------------------------|--|
| fine positioning resolution | μ° | |
| fine angular positioning range @ 300 K | 12 m° | |
| input DC voltage range @ 300 K | 0 - 100 V | |
| Accuracy of Movement | | |
| repeatability of step sizes | typically 5 % over full range | |
| typ. forward / backward step asymmetry | 10 % | |
| wobble | 6 mrad | |
| Working Conditions | | |
| mounting orientation | arbitrary | |
| minimum pressure (/RT) | ambient | |
| temperature range (/RT) | 273K 373K | |
| Connectors and Feedthroughs | | |
| cable | 50 cm cable with connector | |
| connector type | 14-pole connector | |
| connector type (/HV, /UHV) | 15-pin D-Sub connector | |
| Versions | | |
| /RT version | 1006205 | |

Technical Drawings







